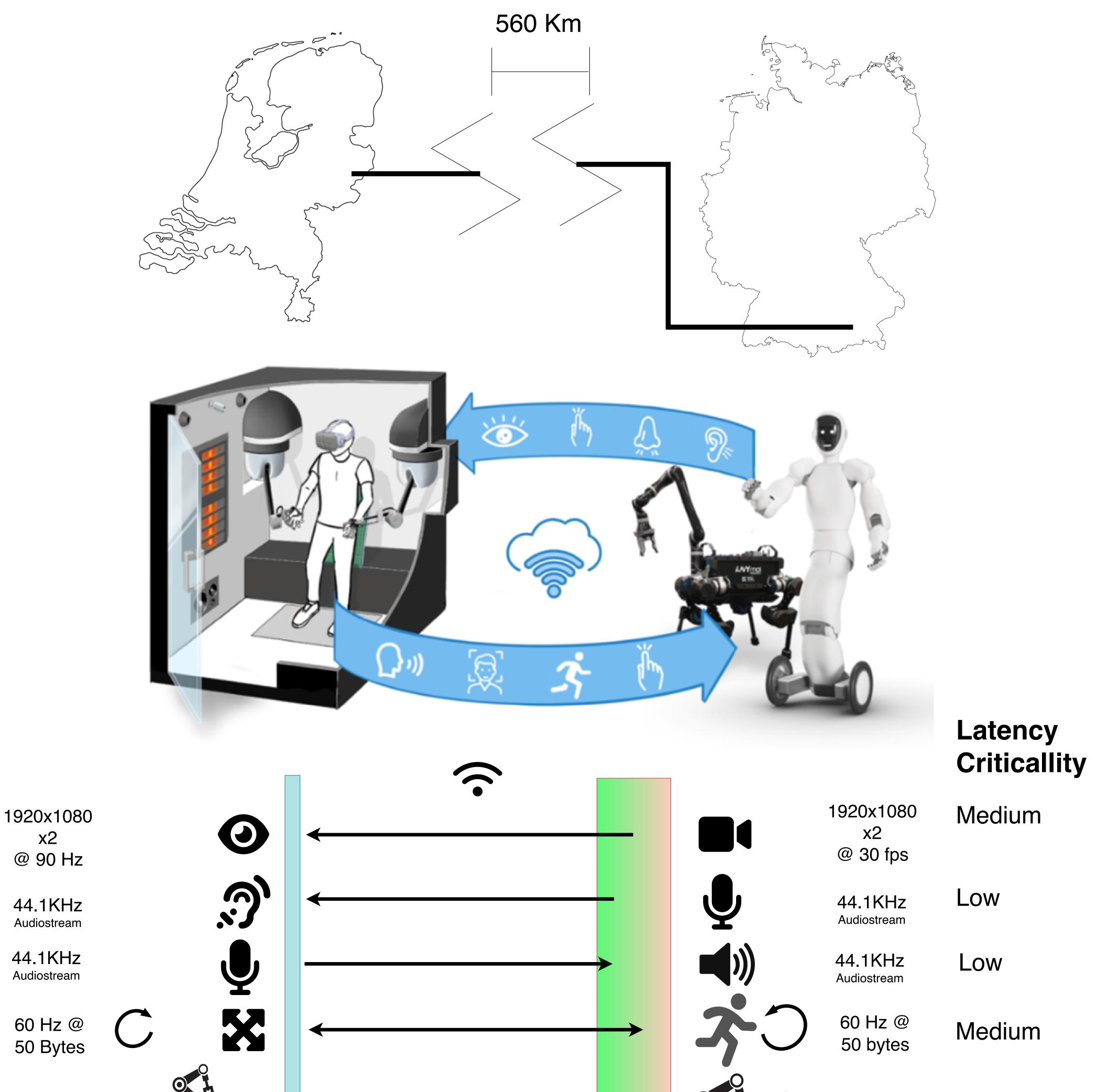
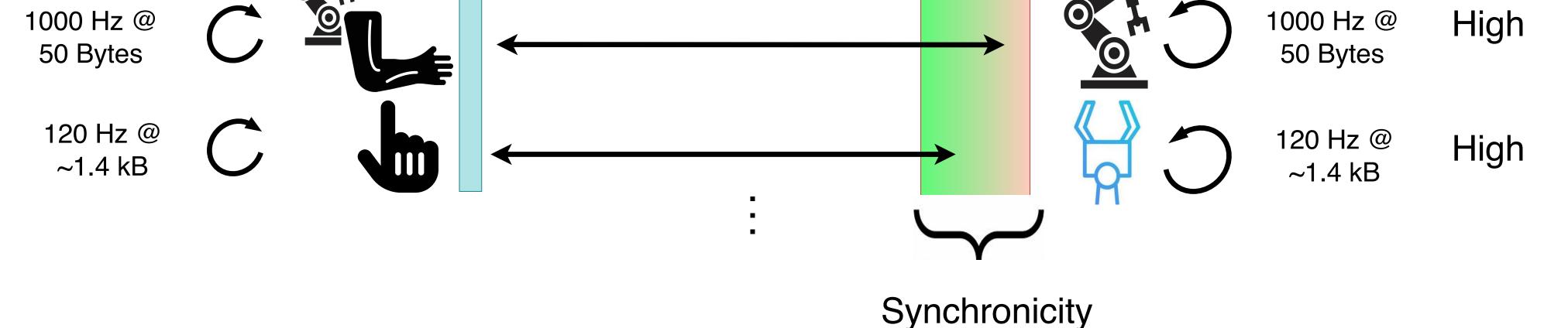


Communication Challenges in Tele-Operated Robotics





Communication Challenge

QoS optimalisation of multiple channels which need lots of bandwidth, at high update frequency, low latency, and synchronicity between the channels

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